MATH 245 Linear Algebra 2, Solutions to Assignment 3

1: Let
$$u_1 = \begin{pmatrix} 1 \\ 0 \\ 1 \\ -1 \end{pmatrix}$$
, $u_2 = \begin{pmatrix} 2 \\ 1 \\ 1 \\ 0 \end{pmatrix}$, $u_3 = \begin{pmatrix} 1 \\ -3 \\ 2 \\ 1 \end{pmatrix}$ and $x = \begin{pmatrix} 1 \\ 1 \\ 7 \\ 3 \end{pmatrix}$. Let $\mathcal{U} = \{u_1, u_2, u_3\}$ and let $U = \text{Span } \mathcal{U}$. Find $\text{Proj}_U(x)$ in the following three ways.

(a) Let $A = (u_1, u_2, u_3) \in M_{4 \times 3}$ then use the formula $\operatorname{Proj}_U(x) = Ay$ where y is the solution to $A^t A y = A^t x$. Solution: We have

$$A^{t}A = \begin{pmatrix} 1 & 0 & 1 & -1 \\ 2 & 1 & 1 & 0 \\ 1 & -3 & 2 & 1 \end{pmatrix} \begin{pmatrix} 1 & 2 & 1 \\ 0 & 1 & -3 \\ -1 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 3 & 3 & 2 \\ 3 & 6 & 1 \\ 2 & 1 & 15 \end{pmatrix}$$

$$A^{t}x = \begin{pmatrix} 1 & 0 & 1 & -1 \\ 2 & 1 & 1 & 0 \\ 1 & -3 & 2 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \\ 7 \\ 3 \end{pmatrix} = \begin{pmatrix} 5 \\ 10 \\ 15 \end{pmatrix}$$

$$(A^{t}A|A^{t}x) = \begin{pmatrix} 3 & 3 & 2 & | & 5 \\ 3 & 6 & 1 & | & 10 \\ 2 & 1 & 15 & | & 15 \end{pmatrix} \sim \begin{pmatrix} 1 & 2 & -13 & | & 10 \\ 3 & 6 & 1 & | & 10 \\ 2 & 1 & 15 & | & 15 \end{pmatrix} \sim \begin{pmatrix} 1 & 2 & -13 & | & 10 \\ 0 & 3 & -41 & | & -35 \end{pmatrix}$$

$$\sim \begin{pmatrix} 1 & 2 & -13 & | & 10 \\ 0 & 3 & -41 & | & -35 \\ 0 & 0 & 1 & | & 1 \end{pmatrix} \sim \begin{pmatrix} 1 & 2 & 0 & | & 3 \\ 0 & 3 & 0 & | & 6 \\ 0 & 0 & 1 & | & 1 \end{pmatrix} \sim \begin{pmatrix} 1 & 2 & 0 & | & 3 \\ 0 & 3 & 0 & | & 6 \\ 0 & 0 & 1 & | & 1 \end{pmatrix} \sim \begin{pmatrix} 1 & 2 & 0 & | & 3 \\ 0 & 1 & 0 & | & 2 \\ 0 & 0 & 1 & | & 1 \end{pmatrix} \sim \begin{pmatrix} -1 \\ 0 & 1 & -3 \\ 0 & 0 & 1 & | & 1 \end{pmatrix}$$

and so

$$y = \begin{pmatrix} -1\\ 2\\ 1 \end{pmatrix} \text{ and } \operatorname{Proj}_{U}(x) = Ay = \begin{pmatrix} 1 & 2 & 1\\ 0 & 1 & -3\\ 1 & 1 & 2\\ -1 & 0 & 1 \end{pmatrix} \begin{pmatrix} -1\\ 2\\ 1 \end{pmatrix} = \begin{pmatrix} 4\\ -1\\ 3\\ 2 \end{pmatrix}.$$

(b) Apply the Gram-Schmidt Procedure to the basis \mathcal{U} to obtain an orthogonal basis $\mathcal{V} = \{v_1, v_2, v_3\}$ for U, then use the formula $\operatorname{Proj}_U(x) = \sum_{i=1}^3 \frac{x \cdot v_i}{|v_i|^2} v_i$.

Solution: We let

$$\begin{aligned} v_1 &= u_1 = \begin{pmatrix} 1\\0\\1\\-1 \end{pmatrix} \\ v_2 &= u_2 - \frac{u_2 \cdot v_1}{|v_1|^2} v_1 = \begin{pmatrix} 2\\1\\1\\0 \end{pmatrix} - \frac{3}{3} \begin{pmatrix} 1\\0\\1\\-1 \end{pmatrix} = \begin{pmatrix} 1\\1\\0\\1\\-1 \end{pmatrix} \\ v_3 &= u_3 - \frac{u_3 \cdot v_1}{|v_1|^2} v_1 - \frac{u_3 \cdot v_2}{|v_2|^2} v_2 = \begin{pmatrix} 1\\-3\\2\\1 \end{pmatrix} - \frac{2}{3} \begin{pmatrix} 1\\0\\1\\-1 \end{pmatrix} + \frac{1}{3} \begin{pmatrix} 1\\0\\1\\-1 \end{pmatrix} \\ = \frac{1}{3} \begin{pmatrix} 2\\-8\\4\\6 \end{pmatrix} = \frac{2}{3} \begin{pmatrix} 1\\-4\\2\\3 \end{pmatrix} .\end{aligned}$$

Then

$$\operatorname{Proj}_{U}(x) = \frac{x \cdot v_{1}}{|v_{1}|^{2}} v_{1} - \frac{x \cdot v_{2}}{|v_{2}|^{2}} v_{2} - \frac{x \cdot v_{3}}{|v_{3}|^{2}} v_{3} = \frac{5}{3} \begin{pmatrix} 1\\0\\1\\-1 \end{pmatrix} + \frac{5}{3} \begin{pmatrix} 1\\1\\0\\1 \end{pmatrix} + \frac{20}{30} \begin{pmatrix} 1\\-4\\2\\3 \end{pmatrix} = \frac{1}{3} \begin{pmatrix} 12\\-3\\9\\6 \end{pmatrix} = \begin{pmatrix} 1\\-1\\3\\2 \end{pmatrix}.$$

(c) Find $w = X(u_1, u_2, u_3)$ so that $\{w\}$ is a basis for U^{\perp} , then calculate $\operatorname{Proj}_U(x) = x - \operatorname{Proj}_w(x)$. Solution: We let

$$w = X(u_1, u_2, u_3) = X\left(\begin{pmatrix} 1\\0\\1\\-1 \end{pmatrix}, \begin{pmatrix} 2\\1\\1\\0 \end{pmatrix}, \begin{pmatrix} 1\\-3\\2\\1 \end{pmatrix}\right)$$
$$= \left(-\begin{vmatrix} 0 & 1 & -3\\1 & 1 & 2\\-1 & 0 & 1 \end{vmatrix}, \begin{vmatrix} 1 & 2 & 1\\1 & 1 & 2\\-1 & 0 & 1 \end{vmatrix}, -\begin{vmatrix} 1 & 2 & 1\\0 & 1 & -3\\-1 & 0 & 1 \end{vmatrix}, \begin{vmatrix} 1 & 2 & 1\\0 & 1 & -3\\1 & 1 & 2 \end{vmatrix} \right)^t$$
$$= \begin{pmatrix} -(-2 - 1 - 3)\\(1 - 4 - 2 + 1)\\-(1 + 6 + 1)\\(2 - 6 + 3 - 1) \end{pmatrix} = \begin{pmatrix} 6\\-4\\-8\\-2 \end{pmatrix} = 2\begin{pmatrix} 3\\-2\\-4\\-1 \end{pmatrix}$$

and so

$$\operatorname{Proj}_{U}(x) = x - \frac{x \cdot w}{|w|^{2}} w = \begin{pmatrix} 1\\1\\7\\3 \end{pmatrix} + \frac{30}{30} \begin{pmatrix} 3\\-2\\-4\\-1 \end{pmatrix} = \begin{pmatrix} 4\\-1\\3\\2 \end{pmatrix} \,.$$

2: Consider the vector space $P_2 = P_2(\mathbf{R})$ as a subspace of the vector space

$$\mathcal{C}((0,1)) = \mathcal{C}((0,1), \mathbf{R}) = \left\{ f: (0,1) \to \mathbf{R} \middle| f \text{ is continuous, and } \int_0^1 f(x)^2 dx \text{ converges.} \right\}$$
 with the inner product given by $\langle f, g \rangle = \int_0^1 fg.$

(a) Let $p_0 = 1$, $p_1 = x$ and $p_2 = x^2$. Apply the Gram-Schmidt Procedure to the basis $\{p_0, p_1, p_2\}$ to obtain an orthogonal basis $\{q_0, q_1, q_2\}$ for P_2 .

Solution: We let

$$\begin{aligned} q_0 &= p_0 = 1 \\ q_1 &= p_1 - \frac{\langle p_1, q_0 \rangle}{|q_0|^2} q_0 = x - \frac{1/2}{1} \cdot 1 = x - \frac{1}{2} \text{, and} \\ q_2 &= p_2 - \frac{\langle p_2, q_0 \rangle}{|q_0|^2} q_0 - \frac{\langle p_2, q_1 \rangle}{|q_1|^2} q_1 = x^2 - \frac{1/3}{1} \cdot 1 - \frac{1/12}{1/12} \left(x - \frac{1}{2}\right) = x^2 - \frac{1}{3} - \left(x - \frac{1}{2}\right) = x^2 - x + \frac{1}{6} \text{,} \end{aligned}$$

where we made use of the following equalities

$$\langle p_1, q_0 \rangle = \int_0^1 x \, dx = \frac{1}{2}$$

$$|q_0|^2 = \int_0^1 1 \, dx = 1$$

$$\langle p_2, q_0 \rangle = \int_0^1 x^2 \, dx = \frac{1}{3}$$

$$\langle p_2, q_1 \rangle = \int_0^1 x^2 \left(x - \frac{1}{2} \right) \, dx = \int_0^1 x^3 - \frac{1}{2} \, x^2 \, dx = \frac{1}{4} - \frac{1}{6} = \frac{1}{12}$$

$$|q_1|^2 = \int_0^1 \left(x - \frac{1}{2} \right)^2 \, dx = \int_0^1 x^2 - x + \frac{1}{4} \, dx = \frac{1}{3} - \frac{1}{2} + \frac{1}{4} = \frac{1}{12}$$

We also note (for use in parts (b) and (c)) that

$$|q_2|^2 = \int_0^1 \left(x^2 - x + \frac{1}{6}\right)^2 = \int_0^1 x^4 - 2x^3 + \frac{4}{3}x^2 - \frac{1}{3}x + \frac{1}{36} dx = \frac{1}{5} - \frac{1}{2} + \frac{4}{9} - \frac{1}{6} + \frac{1}{36} = \frac{1}{180}$$

(b) Find the quadratic $f \in P_2$ which minimizes $\int_0^1 (f(x) - x^{-1/3})^2 dx$.

Solution: Write $g(x) = x^{-1/3}$. Note that $\int_0^1 (f(x) - x^{-1/3})^2 dx = |f - g|^2$. To minimize |f - g| we must choose

$$f = \operatorname{Proj}_{P_2}(g) = \frac{\langle g, q_0 \rangle}{|q_0|^2} q_0 + \frac{\langle g, q_1 \rangle}{|q_1|^2} q_1 + \frac{\langle g, q_2 \rangle}{|q_2|^2} q_2$$

= $\frac{3/2}{1} \cdot 1 + \frac{-3/20}{1/12} \left(x - \frac{1}{2} \right) + \frac{1/40}{1/180} \left(x^2 - x + \frac{1}{6} \right)$
= $\frac{3}{2} - \frac{9}{5} \left(x - \frac{1}{2} \right) + \frac{9}{2} \left(x^2 - x + \frac{1}{6} \right) = \frac{9}{2} x^2 - \frac{63}{10} x + \frac{63}{20}$

where me made use of some equalities from part (a) along with the following

$$\langle g, q_0 \rangle = \int_0^1 x^{-1/3} \, dx = \frac{3}{2}$$

$$\langle g, q_1 \rangle = \int_0^1 \left(x - \frac{1}{2} \right) x^{-1/3} \, dx = \int_0^1 x^{2/3} - \frac{1}{2} x^{-1/3} \, dx = \frac{3}{5} - \frac{3}{4} = -\frac{3}{20}$$

$$\langle g, q_2 \rangle = \int_0^1 \left(x^2 - x + \frac{1}{6} \right) x^{-1/3} \, dx = \int_0^1 x^{5/3} - x^{2/3} + \frac{1}{6} x^{-1/3} \, dx = \frac{3}{8} - \frac{3}{5} + \frac{1}{4} = \frac{1}{40} \, .$$

(c) Given that $f \in \mathcal{C}((0,1))$ with $\int_0^1 f(x) dx = 3$, $\int_0^1 x f(x) dx = 2$ and $\int_0^1 x^2 f(x) dx = 1$, find the minimum possible value for $\int_0^1 f(x)^2 dx$.

Solution: Since $\langle f,1\rangle=3,\,\langle f,x\rangle=2$ and $\langle f,x^2\rangle=1$ we have

$$\begin{split} \langle f, q_0 \rangle &= \langle f, 1 \rangle = 3 \\ \langle f, q_1 \rangle &= \langle f, x - \frac{1}{2} \rangle = \langle f, x \rangle - \frac{1}{2} \langle f, 1 \rangle = 2 - \frac{3}{2} = \frac{1}{2} \text{ , and} \\ \langle f, q_2 \rangle &= \langle f, x^2 - x + \frac{1}{6} \} = \langle f, x^2 \rangle - \langle f, x \rangle + \frac{1}{6} \langle f, 1 \rangle = 1 - 2 + \frac{1}{2} = -\frac{1}{2} \end{split}$$

and hence

$$\operatorname{Proj}_{P_2}(f) = \frac{\langle f, q_0 \rangle}{|q_0|^2} q_0 + \frac{\langle f, q_1 \rangle}{|q_1|^2} q_1 + \frac{\langle f, q_2 \rangle}{|q_2|^2} q_2 = \frac{3}{1} q_0 + \frac{1/2}{1/12} q_1 + \frac{-1/2}{180} q_2 = 3q_0 + 6q_1 - 90q_2.$$

Let $g = 3q_0 + 6q_1 - 90q_2$. Given that $f \in \mathcal{C}(0, 1)$ with $\operatorname{Proj}_{P_2}(f) = g$, in order to minimize $|f|^2 = \int_0^1 f(x)^2 dx$ we must choose f = g since, by Pythagoras' Theorem, we have $|f|^2 = |g|^2 + |f - g|^2 \ge |g|^2$ with equality only when |f - g| = 0. Thus the minimum possible value for $|f|^2$ is $|g|^2 = \langle 3q_0 + 6q_1 - 90q_2, 3q_0 + 6q_1 - 90q_2 \rangle = 9|q_0|^2 + 36|q_1|^2 + 8100|q_2|^2 = 9 + \frac{36}{12} + \frac{8100}{180} = 9 + 3 + 45 = 57$. **3:** Let U and V be inner product spaces over **R**. An **isometry** from U to V is a surjective map $F: U \to V$ which preserves distance, so that for all $x, y \in U$ we have |F(x) - F(y)| = |x - y|. An inner product space **isomorphism** from U to V is a bijective linear map $G: U \to V$ which preserves inner product, so that for all $x, y \in U$ we have $\langle G(x), G(y) \rangle = \langle x, y \rangle$. Show that, in the case that U and V are finite dimensional, every isometry $F: U \to V$ is of the form F(x) = G(x) + b for some inner product space isomorphism G and some $b \in V$.

Solution: Let $F: U \to V$ be an isometry. Note that F is bijective since it is surjective by definition and it is injective since, for $x, y \in U$ we have

$$F(x) = F(y) \Longrightarrow |F(x) - F(y)| = 0 \Longrightarrow |x - y| = 0 \Longrightarrow x = y$$

Define $G: U \to V$ by

$$G(x) = F(x) - F(0)$$

so that we have F(x) = G(x) + b with b = F(0). Note that G is bijective, G(0) = 0 and G preserves distance since for $x, y \in U$ we have

$$|G(x) - G(y)| = |F(x) - F(0) - F(y) + F(0)| = |F(x) - F(y)| = |x - y|.$$

It follows from the Polarization Identity that G preserves inner product, indeed for $x, y \in U$ we have

$$\langle G(x), G(y) \rangle = \frac{1}{2} (|G(x)|^2 + |G(y)|^2 - |G(x) - G(y)|^2) , \text{ by the Polarization Identity}$$

$$= \frac{1}{2} (|G(x) - G(0)|^2 + |G(y) - G(0)|^2 - |G(x) - G(y)|^2) , \text{ since } G(0) = 0$$

$$= \frac{1}{2} (|x - 0|^2 + |y - 0|^2 - |x - y|^2) , \text{ since } G \text{ preserves distance}$$

$$= \frac{1}{2} (|x|^2 + |y|^2 - |x - y|^2)$$

$$= \langle x, y \rangle , \text{ by the Polarization Identity.}$$

Finally, we provide two proofs that G is linear. For the first proof (which is valid even when U and V are infinite-dimensional), let $x, y \in U$ and $t \in \mathbf{R}$. Then we have G(x + ty) = G(x) + tG(y) since

$$\begin{split} \left|G(x+ty) - \left(G(x) + tG(y)\right)\right|^2 &= \left|G(x+ty) - G(x) - tG(y)\right|^2 \\ &= \left\langle G(x+ty) - G(x) - tG(y), G(x+ty) - G(x) - tG(y) \right\rangle \\ &= \left\langle G(x+ty), G(x+ty) \right\rangle - \left\langle G(x+ty), G(x) \right\rangle - t \left\langle G(x), G(y) \right\rangle \\ &- \left\langle G(x), G(x+ty) \right\rangle + \left\langle G(y), G(x) \right\rangle + t \left\langle G(x), G(y) \right\rangle \\ &- t \left\langle G(y), G(x+ty) \right\rangle + t \left\langle G(y), G(x) \right\rangle + t^2 \left\langle G(y), G(y) \right\rangle \\ &= \left\langle x + ty, x + ty \right\rangle - \left\langle x + ty, x \right\rangle - t \left\langle x + ty, y \right\rangle \\ &- \left\langle y, x + ty \right\rangle + t \left\langle y, x \right\rangle + t^2 \left\langle y, y \right\rangle \\ &= \left\langle x + ty - x - ty, x + ty - x - ty \right\rangle \\ &= 0 \,. \end{split}$$

For the second proof, we begin by noting that G^{-1} also preserves inner product. Indeed, given $u, v \in V$, by writing $x = G^{-1}(u)$ and $y = G^{-1}(v)$ and using the fact that G preserves inner product, we have

$$\langle G^{-1}(u), G^{-1}(v) \rangle = \langle x, y \rangle = \langle G(x), G(y) \rangle = \langle u, v \rangle.$$

Next we show that $\dim(U) = \dim(V)$. Let $\mathcal{U} = \{u_1, \dots, u_l\}$ be an orthonormal basis for U, and let $\mathcal{V} = \{G(u_1), \dots, G(u_l)\}$. Since G preserves inner product, \mathcal{V} is an orthonormal set, hence \mathcal{V} is linearly independent, hence $\dim U = l \leq \dim V$. Similarly, since G^{-1} also preserves inner product, $\dim V \leq \dim U$. Thus $\dim U = \dim V$ and \mathcal{V} is an orthonormal basis for V. Finally we note that G is linear since for $x = \sum_{i=1}^{l} t_i u_i \in U$ we can write $G(x) = \sum_{i=1}^{l} s_i G(u_i)$ for some $s_i \in \mathbf{R}$, and then for each i we have $s_i = \langle G(x), G(u_i) \rangle$, since \mathcal{V} is orthonormal $= \langle x, u_i \rangle$, since \mathcal{G} preserves inner product $= t_i$, since \mathcal{U} is orthonormal.

4: Identify \mathbf{C}^n with \mathbf{R}^{2n} using the bijection $\phi: \mathbf{C}^n \to \mathbf{R}^{2n}$ given by

$$\phi(x_1 + i y_1, \dots, x_n + i y_n)^t = (x_1, y_1, \dots, x_n, y_n)^t.$$

(a) Determine whether, for all vectors $u, v \in \mathbb{C}^n$, u is orthogonal to v in \mathbb{C}^n if and only if $\phi(u)$ is orthogonal to $\phi(v)$ in \mathbb{R}^{2n} .

Solution: Note first that for
$$u, v \in \mathbb{C}^n$$
 given by $u = \begin{pmatrix} a_1 + i \, b_1 \\ \vdots \\ a_n + i \, b_n \end{pmatrix}$ and $v = \begin{pmatrix} c_1 + i \, d_1 \\ \vdots \\ c_n + i \, d_n \end{pmatrix}$, we have
 $\langle u, v \rangle = \sum_{k=1}^n (a_k + i \, b_k)(c_k - i \, d_k) = \sum_{k=1}^n (a_k c_k + b_k d_k) + i \sum_{k=1}^n (-a_k d_k + b_k c_k)$, and
 $\phi(u) \cdot \phi(v) = \sum_{k=1}^n (a_k c_k + b_k d_k) = \operatorname{Re}(\langle u, v \rangle).$

It follows that if $\langle u, v \rangle = 0$ then $\phi(u) \cdot \phi(v) = 0$, but the converse does not hold. For example for $u = e_1$ and $v = i e_1$ (where e_1 is the first standard basis vector) we have $\langle u, v \rangle = i$ and $\phi(u) \cdot \phi(v) = 0$.

(b) Determine whether, for all complex subspaces $U, V \subset \mathbb{C}^n$, U is orthogonal to V in \mathbb{C}^n if and only if $\phi(U)$ is orthogonal to $\phi(V)$ in \mathbb{R}^{2n} .

Solution: This is true. Suppose first that U is orthogonal to V in \mathbb{C}^n (so $\langle u, v \rangle = 0$ for all $u \in U, v \in V$). Given $x \in \phi(U)$ and $y \in \phi(V)$, let $u = \phi^{-1}(x)$ and $v = \phi^{-1}(y)$. Then (by our work in part (a))

$$x \cdot y = \phi(u) \cdot \phi(v) = \operatorname{Re}(\langle u, v \rangle) = \operatorname{Re}(0) = 0.$$

Thus $\phi(U)$ is orthogonal to $\phi(V)$ in \mathbb{R}^{2n} . Conversely, suppose that $\phi(U)$ is orthogonal to $\phi(V)$ in \mathbb{R}^{2n} . Let $u \in U$ and $v \in V$. Note that we also have $iv \in V$. Then

$$0 = \phi(u) \cdot \phi(v) = \operatorname{Re}(\langle u, v \rangle) \text{, and}$$

$$0 = \phi(u) \cdot \phi(iv) = \operatorname{Re}(\langle u, iv \rangle) = \operatorname{Re}(-i\langle u, v \rangle) = \operatorname{Im}(\langle u, v \rangle).$$

Since $\operatorname{Re}(\langle u, v \rangle) = 0 = \operatorname{Im}(\langle u, v \rangle)$, it follows that $\langle u, v \rangle = 0$. Thus U is orthogonal to V in \mathbb{C}^n .

5: Identify \mathbf{C}^n with \mathbf{R}^{2n} using the map ϕ from question 4. Given two 1-dimensional complex subspaces $U, V \subset \mathbf{C}^n$, we define the **angle** between U and V to be

angle
$$(U, V) = \cos^{-1} \frac{|\langle u, v \rangle|}{|u||v|}$$
, where $0 \neq u \in U$, $0 \neq v \in V$.

(a) Explain why this definition is well-defined.

Solution: The definition makes sense firstly because $0 \leq \frac{|\langle u, v \rangle|}{|u||v|} \leq 1$ by Cauchy's Inequality and secondly because the definition does not depend on the choice of u and v; indeed given $0 \neq u' \in U$ and $0 \neq v' \in V$ we have u' = su and v' = tv for some $0 \neq s, t \in \mathbf{C}$ and so

$$\frac{|\langle u',v'\rangle|}{|u'||v'|} = \frac{\langle su,tv\rangle|}{|su||tv|} = \frac{|s\overline{t}\langle u,v\rangle|}{|s||u||t||v|} = \frac{|\langle u,v\rangle|}{|u||v|} \,.$$

(b) Determine whether, for all 1-dimensional complex subspaces $U, V \subset \mathbb{C}^n$, the angle between U and V in \mathbb{C}^n is equal to the angle between $\phi(U)$ and $\phi(V)$ in \mathbb{R}^{2n} .

Solution: This is true. When U = V we have $\phi(U) = \phi(V)$ and $\operatorname{angle}(U, V) = 0 = \operatorname{angle}(\phi(U), \phi(V))$. Suppose that $U \neq V$. Note that this implies that $U \cap V = \{0\}$ (since U and V are 1-dimensional). Let $X = \phi(U)$ and $Y = \phi(V)$. Note that X and Y are both 2-dimensional with $X \cap Y = \phi(U) \cap \phi(V) = \phi(U \cap V) = \{0\}$. For $0 \neq u, v \in \mathbb{C}^n$ write

$$A(u, v) = \operatorname{angle}(\operatorname{Span}_{\mathbf{C}}\{u\}, \operatorname{Span}_{\mathbf{C}}\{v\}) = \cos^{-1} \frac{|\langle u, v \rangle}{|u||v|}$$

and for $0 \neq x, y \in \mathbf{R}^{2n}$ write

$$B(x,y) = \operatorname{angle}\left(\operatorname{Span}_{\mathbf{R}}\{x\}, \operatorname{Span}_{\mathbf{R}}\{y\}\right) = \cos^{-1}\frac{|x \cdot y|}{|x||y|} = \begin{cases} \theta(x,y) & \text{if } 0 \le \theta(x,y) \le \frac{\pi}{2} \\ \pi - \theta(x,y) & \text{if } \frac{\pi}{2} \le \theta(x,y) \le \pi \end{cases}$$

With this notation we have

$$\begin{split} & \operatorname{angle}(U,V) = A(u,v) \text{ where } 0 \neq u \in U \text{ , } 0 \neq v \in V \\ & \operatorname{angle}(X,Y) = \min \left\{ B(x,y) \middle| 0 \neq x \in X \text{ , } 0 \neq y \in Y \right\}. \end{split}$$

Recall that by our work in 4(a), when $x = \phi(u)$ and $y = \phi(v)$ we have $x \cdot y = \operatorname{Re}(\langle u, v \rangle)$. Also note that $|x|^2 = \langle x, x \rangle = \operatorname{Re}(\langle u, u \rangle) = \operatorname{Re}(|u|^2) = |u|^2$ so that |x| = |u|, and similarly |y| = |v|.

Given $0 \neq x \in X$ and $0 \neq y \in Y$, let $u = \phi^{-1}(x)$ and $v = \phi^{-1}(y)$. Note that $0 \neq u \in U$ and $0 \neq v \in V$ and we have $|x \cdot y| = |\operatorname{Re}(\langle u, v \rangle)| \leq |\langle u, v \rangle|$ so that $\frac{|x \cdot y|}{|x||y|} \leq \frac{|\langle u, v \rangle|}{|u||v|}$ and hence $B(x, y) \geq A(u, v)$. It follows that $\operatorname{angle}(U, V) \leq \operatorname{angle}(X, Y)$.

Conversely, given $0 \neq u \in U$ and $0 \neq v \in V$, write $\langle u, v \rangle = r e^{i\theta}$ with $r = |\langle u, v \rangle|$. Note that $0 \neq e^{i\theta}v \in V$ and $|e^{i\theta}v| = |v|$. Let $x = \phi(u)$ and $y = \phi(e^{i\theta}v)$ and note that $0 \neq x \in X$ and $0 \neq y \in Y$. We have

$$x \cdot y = \operatorname{Re}\left(\left\langle u, e^{i\,\theta}v\right\rangle\right) = \operatorname{Re}\left(e^{-i\,\theta}\left\langle u, v\right\rangle\right) = \operatorname{Re}\left(e^{-i\,\theta}\,re^{i\,\theta}\right) = \operatorname{Re}(r) = r = |\langle u, v\rangle$$

so that $\frac{|x \cdot y|}{|x||y|} = \frac{|\langle u, v \rangle|}{|u||v|}$ and hence B(x, y) = A(u, v). It follows that $\operatorname{angle}(X, Y) \le \operatorname{angle}(U, V)$.